

# NUMERICAL DIFFERENTIATION

## Numerical Differentiation

It is the process of calculating the value of the derivative of a function at some assigned value of  $x$  from the given set of values  $(x_i, y_i)$ .

To compute  $dy/dx$ , we first replace the exact relation  $y = f(x)$  by the best interpolating polynomial  $y = \phi(x)$  and then differentiate the latter as many times as we desire.

The choice of the interpolation formula to be used, will depend on the assigned value of  $x$  at which  $dy/dx$  is desired.

If the values of  $x$  are equispaced

- $dy/dx$  is required near the beginning of the table, we employ Newton's forward formula.
- If it is required near the end of the table, we use Newton's backward formula.
- For values near the middle of the table,  $dy/dx$  is calculated by means of Stirling's formula.

If the values of  $x$  are not equispaced,

- Use Lagrange's formula or Newton's divided difference formula to represent the function.

### Formulae for Derivatives

Consider the function  $y = f(x)$  which is tabulated for the values  $x_i (= x_0 + ih)$ ,  $i = 0, 1, 2, \dots, n$ .

1. Derivatives using Newton's forward difference formula

Newton's forward interpolation formula is

$$Y(x_0 + \alpha \Delta x) = y_0 + (\alpha \Delta y_0) + \frac{\alpha(\alpha-1)}{2!} (\Delta^2 y_0) + \frac{\alpha(\alpha-1)(\alpha-2)}{3!} (\Delta^3 y_0) + \dots + \frac{\alpha(\alpha-1)(\alpha-2)\dots(\alpha-n+1)}{n!} (\Delta^n y_0)$$

Differentiating both sides w.r.t.  $\alpha$ , we have

$$\frac{dy}{d\alpha} = \Delta y_0 + \frac{(2\alpha-1)}{2!} (\Delta^2 y_0) + \frac{(3\alpha^2-6\alpha+2)}{3!} (\Delta^3 y_0) + \dots$$

Since

$$\alpha = \frac{(x - x_0)}{\Delta x}$$

Therefore

$$\frac{d\alpha}{dx} = \frac{1}{\Delta x} = \frac{1}{h}$$

Now

$$\frac{dy}{d\alpha} \cdot \frac{d\alpha}{dx} = \frac{1}{h} \left[ \Delta y_0 + \frac{(2\alpha-1)}{2!} (\Delta^2 y_0) + \frac{(3\alpha^2-6\alpha+2)}{3!} (\Delta^3 y_0) + \frac{(4\alpha^3-18\alpha^2+22\alpha-6)}{4!} (\Delta^4 y_0) + \dots \dots \right]$$

At  $x = x_0$ ,  $\alpha = 0$ . Hence putting  $\alpha = 0$ ,

$$\left( \frac{dy}{dx} \right)_{x_0} = \frac{1}{h} \left[ \Delta y_0 - \frac{1}{2!} (\Delta^2 y_0) + \frac{1}{3!} (\Delta^3 y_0) - \frac{1}{4!} (\Delta^4 y_0) + \dots \dots \right]$$

Again differentiating (1) w.r.t.  $x$ , we get

$$\frac{d^2y}{dx^2} = \frac{1}{dx} \left( \frac{dy}{d\alpha} \cdot \frac{d\alpha}{dx} \right) = \frac{1}{h} \left[ \frac{2}{2|} (\Delta^2 y_0) + \frac{(6\alpha-6)}{3|} (\Delta^3 y_0) + \frac{(12\alpha^2-36\alpha+22)}{4|} (\Delta^4 y_0) + \dots \dots \right] \frac{1}{h}$$

Putting  $\alpha = 0$ , we obtain

$$\frac{d^2y}{dx^2} = \frac{1}{h^2} \left[ \Delta^2 y_0 - \Delta^3 y_0 + \frac{11}{12} (\Delta^4 y_0) - \frac{5}{6} (\Delta^5 y_0) + \frac{137}{180} (\Delta^6 y_0) + \dots \right]$$

Else: We know that  $1 + \Delta = E = e^{hD}$

$$\therefore hD = \log(1 + \Delta) = \Delta - \frac{1}{2}\Delta^2 + \frac{1}{3}\Delta^3 - \frac{1}{4}\Delta^4 + \dots$$

$$\text{or } D = \frac{1}{h} \left[ \Delta - \frac{1}{2}\Delta^2 + \frac{1}{3}\Delta^3 - \frac{1}{4}\Delta^4 + \dots \right]$$

$$\text{and } D^2 = \frac{1}{h^2} \left[ \Delta - \frac{1}{2}\Delta^2 + \frac{1}{3}\Delta^3 - \frac{1}{4}\Delta^4 + \dots \right]^2 = \frac{1}{h^2} \left[ \Delta^2 - \Delta^3 + \frac{11}{12}\Delta^4 + \dots \right]$$

$$\text{and } D^3 = \frac{1}{h^2} \left[ \Delta^3 - \frac{3}{2}\Delta^4 + \dots \right]$$

Now applying the above identities to  $y_0$ , we get

$$Dy_0 \text{ i.e., } \left(\frac{dy}{dx}\right)_{x_0} = \frac{1}{h} \Delta y_0 - \frac{1}{2} \left[ \Delta^2 y_0 \frac{1}{3} \Delta^3 y_0 - \frac{1}{4} \Delta^4 y_0 + \frac{1}{5} \Delta^5 y_0 - \frac{1}{6} \Delta^6 y_0 + \dots \right]$$

$$\left(\frac{d^2 y}{dx^2}\right) = \frac{1}{h^2} \left[ \Delta^2 y_0 - \Delta^3 y_0 + \frac{11}{12} \Delta^4 y_0 - \frac{5}{6} \Delta^5 y_0 + \frac{137}{180} \Delta^6 y_0 - \dots \right]$$

and  $\left(\frac{d^3 y}{dx^3}\right) = \frac{1}{h^3} \left[ \Delta^2 y_0 - \frac{3}{2} \Delta^4 y_0 + \dots \right]$

## Derivatives using Newton's backward difference formula

Newton's backward interpolation formula is

$$Y(x_n + \alpha \Delta x) = y_n + \alpha (\nabla y_n) + \frac{\alpha(\alpha+1)}{2!} (\nabla^2 y_n) + \frac{\alpha(\alpha+1)(\alpha+2)}{3!} (\nabla^3 y_n) \dots \dots \dots$$

$$\frac{\alpha(\alpha+1)(\alpha+2) \dots \dots \dots (\alpha+n-1)}{n!} (\nabla^n y_n)$$

Differentiating both sides w.r.t.  $\alpha$ , we have

$$\frac{dy}{d\alpha} = \nabla y_n + \frac{2\alpha+1}{2!} (\nabla^2 y_n) + \frac{3\alpha^2+6\alpha+2}{3!} (\nabla^3 y_n) \dots \dots \dots$$

Since

$$\alpha = \frac{(x - x_n)}{\Delta x}$$

Therefore

$$\frac{d\alpha}{dx} = \frac{1}{\Delta x} = \frac{1}{h}$$

Now

$$\frac{dy}{d\alpha} \cdot \frac{d\alpha}{dx} = \frac{1}{h} \left[ \nabla y_n + \frac{2\alpha+1}{2!} (\nabla^2 y_n) + \frac{3\alpha^2+6\alpha+2}{3!} (\nabla^3 y_n) \dots \dots \dots \right]$$

At  $x = x_n$ ,  $\alpha = 0$ . Hence putting  $\alpha = 0$ ,

$$\left( \frac{dy}{dx} \right)_{x_n} = \frac{1}{h} \left[ \nabla y_n + \frac{1}{2} (\nabla^2 y_n) + \frac{1}{3} (\nabla^3 y_n) + \frac{1}{4} (\nabla^4 y_n) + \frac{1}{5} (\nabla^5 y_n) + \dots \dots \dots \right]$$

Again differentiating (1) w.r.t.  $x$ , we get

$$\frac{d^2 y}{dx^2} = \frac{1}{dx} \left( \frac{dy}{d\alpha} \cdot \frac{d\alpha}{dx} \right) = \frac{1}{h} \left[ \frac{2}{2!} (\nabla^2 y_n) + \frac{6\alpha+6}{3!} (\nabla^3 y_n) + \frac{6\alpha^2+18\alpha+11}{4!} (\nabla^4 y_n) \dots \dots \dots \right] \frac{1}{h}$$

Putting  $\alpha = 0$ , we obtain

$$\frac{d^2y}{dx^2} = \frac{1}{h^2} [\nabla^2 y_n + \nabla^3 y_n + \frac{11}{12} \nabla^4 y_n + \frac{5}{6} \nabla^5 y_n + \frac{137}{180} \nabla^6 y_n \dots\dots\dots]$$

Else: We know that  $1 - \nabla = E^{-1} = e^{-hD}$

$$\therefore -hD = \log(1 - \nabla) = -[\nabla + \frac{1}{2} \nabla^2 + \frac{1}{3} \nabla^3 + \frac{1}{3} \nabla^4 + \dots]$$

or 
$$D = \frac{1}{h} \left[ \nabla + \frac{1}{2} \nabla^2 + \frac{1}{3} \nabla^3 + \frac{1}{4} \nabla^4 + \dots \right]$$

$$\therefore D^2 = \frac{1}{h^2} \left[ \nabla + \frac{1}{2} \nabla^2 + \frac{1}{2} \nabla^3 + \dots \right]^2 = \frac{1}{h^2} \left[ \nabla^2 + \nabla^3 + \frac{11}{12} \nabla^4 + \dots \right]$$

Similarly, 
$$D^3 = \frac{1}{h^3} \left[ \nabla^3 + \frac{3}{2} \nabla^4 + \dots \right]$$

Applying these identities to  $y_n$ , we get

$$Dy_n \text{ i.e., } \left( \frac{dy}{dx} \right)_{x_n} = \frac{1}{h} \left[ \nabla y_n + \frac{1}{2} \nabla^2 y_n + \frac{1}{2} \nabla^3 y_n + \frac{1}{4} \nabla^4 y_n + \frac{1}{5} \nabla^5 y_n + \frac{1}{6} \nabla^6 y_n + \dots \right]$$

$$\left( \frac{d^2y}{dx^2} \right)_{x_n} = \frac{1}{h^2} \left[ \nabla^2 y_n + \nabla^3 y_n + \frac{11}{12} \nabla^4 y_n + \frac{5}{6} \nabla^5 y_n + \frac{137}{180} \nabla^6 y_n + \dots \right]$$

## Derivatives using Stirling's central difference formula

Stirling's central difference formula is

$$Y(x_0 + \alpha \Delta x) = y_0 + \alpha (\mu \delta y_0) + \frac{\alpha^2}{2!} (\delta^2 y_0) + \frac{\alpha(\alpha^2 - 1^2)}{3!} (\mu \delta^3 y_0) + \frac{\alpha^2(\alpha^2 - 1^2)}{4!} (\delta^4 y_0) + \frac{\alpha(\alpha^2 - 1^2)(\alpha^2 - 2^2)}{5!} (\mu \delta^5 y_0) + \dots$$

Differentiating both sides w.r.t.  $\alpha$ , we have

$$\frac{dy}{d\alpha} = \mu \delta y_0 + \frac{2\alpha}{2!} \delta^2 y_0 + \frac{3\alpha^2 - 1}{3!} \mu \delta^3 y_0 + \frac{4\alpha^3 - 2\alpha}{4!} \delta^4 y_0 + \frac{4\alpha^3 - 3\alpha^2 - 8\alpha + 4}{5!} (\mu \delta^5 y_0) + \dots$$

Since

$$\alpha = \frac{(x - x_0)}{\Delta x}$$

Therefore

$$\frac{d\alpha}{dx} = \frac{1}{\Delta x} = \frac{1}{h}$$

Now

$$\frac{dy}{d\alpha} \cdot \frac{d\alpha}{dx} = \frac{1}{h} \left[ \mu \delta y_0 + \frac{2\alpha}{2!} \delta^2 y_0 + \frac{3\alpha^2 - 1}{3!} \mu \delta^3 y_0 + \frac{4\alpha^3 - 2\alpha}{4!} \delta^4 y_0 + \frac{4\alpha^3 - 3\alpha^2 - 8\alpha + 4}{5!} (\mu \delta^5 y_0) + \dots \right]$$

At  $x = x_0$ ,  $\alpha = 0$ . Hence putting  $\alpha = 0$ ,

$$\left(\frac{dy}{dx}\right)_{x_0} = \frac{1}{h}[\mu\delta y_0 - \frac{1}{6} \mu\delta^3 y_0 + \frac{1}{30} (\mu\delta^5 y_0)\dots\dots\dots]$$

Again differentiating (1) w.r.t.  $x$ , we get

$$\frac{d^2y}{dx^2} = \frac{1}{h^2}[\delta^2 y_0 - \frac{1}{12} \delta^4 y_0 + \frac{1}{90} (\delta^6 y_0)\dots\dots\dots]$$

## Derivatives using unequally spaced values of argument

(i) Lagrange's interpolation formula is

$$f(x) = \frac{(x-x_1)(x-x_2)\dots(x-x_n)}{(x_0-x_1)(x_0-x_2)\dots(x_0-x_n)} y_0 + \frac{(x-x_0)(x-x_2)\dots(x-x_n)}{(x_1-x_0)(x_1-x_2)\dots(x_1-x_n)} y_1$$

$$+ \dots + \frac{(x-x_0)(x-x_1)\dots(x-x_{n-1})}{(x_n-x_0)(x_n-x_1)\dots(x_n-x_{n-1})} y_n$$

Differentiating both sides w.r.t.  $x$ , we get  $f'(x)$ .

(ii) Newton's divided difference formula is

$$f(x) = y_0 + (x - x_0)[x_0, x_1] + (x - x_0)(x - x_1)[x_0, x_1, x_2] \\ + (x - x_0)(x - x_1)(x - x_2)[x_0, x_1, x_2, x_3] + \dots \\ + (x - x_0)(x - x_1) \cdots (x - x_n)[x_0, x_1, \dots, x_n]$$

Differentiating both sides w.r.t.  $x$ , we obtain

$$f'(x) = [x_0, x_1] + [2x - (x_0 + x_1)][x_0, x_1, x_2] + [3x^2 - 2x(x_0 + x_1 + x_2) \\ + (x_0x_1 + x_1x_2 + x_2x_3)][x_0, x_1, x_2, x_3] + \dots$$