

Finite Word length Effect in

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Digital filters

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The basic fundamental operations involved in DSP algorithms like convolution, correlation, DFT, FFT etc. are multiplication and addition.

These operations are performed using input sequence $x(n)$, impulse sequence $h(n)$ and the co-efficients of the difference equation governing the system.

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The input and output data are stored in register in a digital system or different memory location in the form of binary values.

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The maximum size of the binary information that can be stored in a memory location or register is known as "Word-length".

- * When a register stores an 8-bit data then its wordlength is 8-bit.

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- * Quantization & Coding depends on register wordlength.

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- * Quantization & Coding will introduce error in input data; because analog data has infinite precision but digital equivalent has finite precision.

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There are some errors occurred due to the process of finite precision representation of binary numbers in digital system. These errors are commonly called as "finite word length effects or error".

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* Finite Word length effects in digital filters -

(1) Errors due to quantization of I/p data by A/D converter.

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(2) Error due to quantization of filter co-efficients.

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(3) Errors due to rounding of products in multiplication.

(4) Error due to overflow in addition.

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Representation of Numbers —

(a) fixed point representation

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(b) floating "

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(a) fixed point Representation — Bits allotted for integer & fractional part and so position of binary point is fixed.

Drawback → Due to the fixed integer & fractional

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Par-, too large and too small values cannot be represented.

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Types - (i) Sign magnitude form

$$(2.75)_{10} = (010.1100)_2$$

$$(-2.25)_{10} = \underset{\uparrow}{(110.1100)}_2$$

(ii) One's Complement form (for negative)

(iii) Two's Complement form (" ")

* (b)
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Floating Point Representation :-

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$$N_f = M \times 2^E$$

M = Mantissa \rightarrow it will be in binary fraction formed -

$$0.5 \leq M < 1$$

E = Exponent \rightarrow either a positive or negative integer.

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$$(i) +\frac{7}{10} = +111_2 = 0.1110 \times 2^3 = 0.111 \times 2^{+110_2}$$

$$= \underbrace{0110}_{\text{M}} \underbrace{11}_{\text{E}}$$

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$$(ii) -\frac{7}{10} = -111_2 = 1.1110 \times 2^{-3} = 1.1110 \times 2^{+101_2}$$

$$= \underbrace{11110}_{\text{M}} \underbrace{011}_{\text{E}}$$

Quantization - for Truncation

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In fixed point or floating point arithmetic, the size of the result of the operation may exceed the size of binary used in the number system. In this case, the low order bits has to be eliminated in order to store the result.

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Mentioned \rightarrow * Truncation

* Rounding

* Truncation \rightarrow 8 bits to 4 bits

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$$0.01110011 \rightarrow 0.0111$$

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* Rounding \rightarrow 0.101010 rounded to 4 bits
 $=$
 0.1010 or 0.1011

Rounding error \rightarrow $e_r = \text{Nr} - \text{N}$

\downarrow \downarrow
 Unquantized

Range :-

Quantized number

Or rounded number

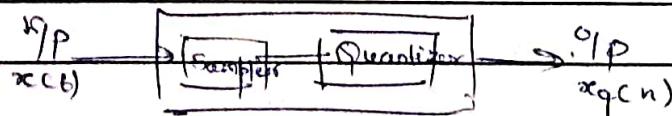
$$-\frac{1}{2^b} \leq e_r < \frac{1}{2^b}$$

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b = no. of rounded

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bits.



Block-diagram of
A/D Conversion

Quantization in filter-coefficients

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The filter coefficients are quantized to word sizes of the register used to store them either by truncation or by rounding.

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* Location of poles & zeros of digital filters directly depends on the value of filter coefficients.

The quantization of the filter coefficients will modify the value of poles and zeros and so the location of poles and zeros will be

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shifted from the desired location. This will create deviation in the frequency response of the system.

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$$\text{Ex:- } H(z) = \frac{1}{(1-0.5z^{-1})(1-0.45z^{-1})}$$

3-bit-coefficients -

$$x(n) \rightarrow (\oplus) \xrightarrow{4 \times 2} = \frac{z^2}{(z-0.5)(z-0.45)} = \frac{1}{(1-0.95z^{-1}+0.225z^{-2})}$$

$$0.95 \xrightarrow{B \rightarrow 3} 0.111_2 \xrightarrow{\text{turn to 3 bits}} 0.111_2 \xrightarrow{B \rightarrow D} 0.075$$

$$0.225 \xrightarrow{B \rightarrow 3} 0.001_2 \xrightarrow{B \rightarrow D} 0.125$$

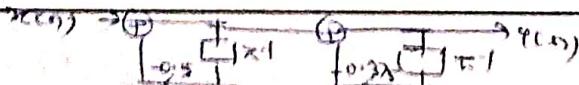
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$$\text{for cascade} \dots H_1(z) = \frac{1}{1-0.5z^{-1}}$$

$$H_2(z) = \frac{1}{1-0.45z^{-1}}$$

$$0.5 \xrightarrow{B \rightarrow 3} 0.100_2 \xrightarrow{B \rightarrow D} 0.5$$

$$0.45 \xrightarrow{B \rightarrow 3} 0.011_2 \xrightarrow{B \rightarrow D} 0.375$$



Quantization in filter - Coefficient

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The filter coefficients are quantized to word sizes of the registers used to store them either by truncation or by rounding.

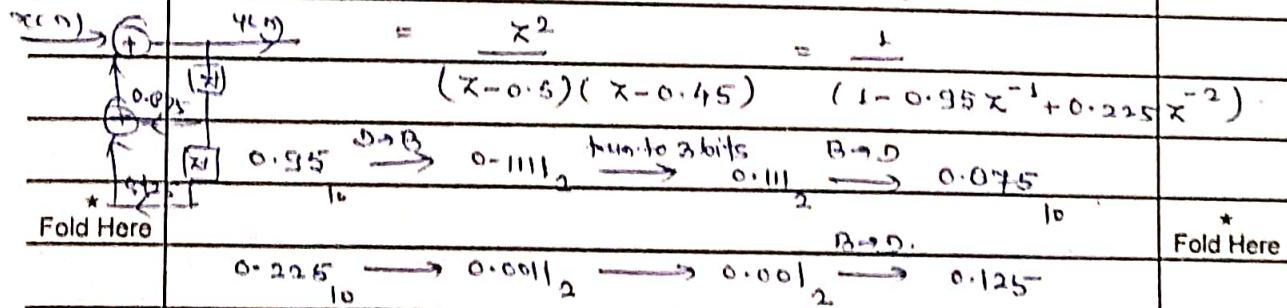
- Location of poles & zeros of digital filters directly depends on the value of filter coefficients. The quantization of the filter coefficients will modify the value of poles and zeros and so the location of poles and zeros will be shifted from the desired location. This will create deviation in the frequency response of the system.

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$$G(z) = \frac{1}{(1-0.5z^{-1})(1-0.45z^{-1})}$$

B-bit coefficient



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$$\text{for denominator: } H_1(z) = \frac{1}{1-0.5z^{-1}}$$

$$H_2(z) = \frac{1}{1-0.45z^{-1}}$$

$$0.5 \xrightarrow{\text{B-to-D}} 0.100_2 \xrightarrow{\text{B-to-D}} 0.10_10$$

$$0.45 \xrightarrow{\text{B-to-D}} 0.011_2 \xrightarrow{\text{B-to-D}} 0.01_2 \xrightarrow{\text{B-to-D}} 0.375$$

