

## **CHAPTER 3**

# **INVERSION BY PARTIAL FRACTIONS**

- We now wish to develop methods for inverting the transforms to obtain the solution in the time domain
- The equations to be solved are all of the general form

$$a_n \frac{d^n x}{dt^n} + a_{n-1} \frac{d^{n-1} x}{dt^{n-1}} + \cdots + a_1 \frac{dx}{dt} + a_0 x = r(t)$$

- The unknown function of time is  $x(t)$ , and  $a_n, a_{n-1}, \dots, a_1, a_0$  are constants.
- The given function  $r(t)$  is called the *forcing function*.
- In addition, for all problems of interest in control system analysis, the initial conditions are given.
- In other words, values of  $x, dx/dt, \dots, d^{n-1}x/dt^{n-1}$  are specified at time 0.
- The problem is to determine  $x(t)$  for all  $t > 0$ .

# PARTIAL FRACTIONS

$$\frac{dx}{dt} + x = 1$$
$$x(0) = 0$$

Application of the Laplace transform yields

$$sx(s) + x(s) = \frac{1}{s}$$
$$x(s) = \frac{1}{s(s+1)}$$

The theory of partial fractions enables us to write this as

$$x(s) = \frac{1}{s(s+1)} = \frac{A}{s} + \frac{B}{s+1}$$
$$A = 1$$
$$B = -1$$

Now that we've found  $A$  and  $B$ , we have

$$x(s) = \frac{1}{s(s+1)} = \frac{1}{s} - \frac{1}{s+1}$$

$$x(t) = 1 - e^{-t}$$

$$\frac{d^3x}{dt^3} + 2\frac{d^2x}{dt^2} - \frac{dx}{dt} - 2x = 4 + e^{2t}$$

$$x(0) = 1 \quad x'(0) = 0 \quad x''(0) = -1$$

Taking the Laplace transform of both sides yields

$$\left[ s^3x(s) - s^2 + 1 \right] + 2\left[ s^2x(s) - s \right] - \left[ sx(s) - 1 \right] - 2x(s) = \frac{4}{s} + \frac{1}{s-2}$$

**Solving algebraically for  $x(s)$ , we find**

$$x(s) = \frac{s^4 - 6s^2 + 9s - 8}{s(s-2)(s^3 + 2s^2 - s - 2)}$$

The cubic in the denominator may be factored, and  $x(s)$  is expanded in partial fractions.

$$x(s) = \frac{s^4 - 6s^2 + 9s - 8}{s(s-2)(s+1)(s+2)(s-1)} = \frac{A}{s} + \frac{B}{s-2} + \frac{C}{s+1} + \frac{D}{s+2} + \frac{E}{s-1}$$

To find  $A$ , multiply both sides of Eq. by  $s$  and then set  $s = 0$ ;

The result is

$$A = \frac{-8}{(-2)(1)(2)(-1)} = -2$$

To determine	Multiply Eq. (3.8) by	and set $s$ to	Result
$B$	$s - 2$	2	$B = \frac{1}{12}$
$C$	$s + 1$	-1	$C = \frac{11}{3}$
$D$	$s + 2$	-2	$D = -\frac{17}{12}$
$E$	$s - 1$	1	$E = \frac{2}{3}$

Accordingly, the solution to the problem is

$$x(t) = -2 + \frac{1}{12}e^{2t} + \frac{11}{3}e^{-t} - \frac{17}{12}e^{-2t} + \frac{2}{3}e^t$$

A comparison between this method and the classical method,

$$s^3 + 2s^2 - s - 2 = 0$$

the roots 1, 2, and -1. Thus, the complementary solution is

$$x_c(t) = C_1e^{-t} + C_2e^{-2t} + C_3e^t$$

## Inversion of a transform that has complex roots in the denominator

$$\frac{d^2x}{dt^2} + 2\frac{dx}{dt} + 2x = 2$$
$$x(0) = 0 \quad x'(0) = 0$$

Application of the Laplace transform yields

$$x(s) = \frac{2}{s(s^2 + 2s + 2)}$$

The quadratic term in the denominator may be factored by use of the quadratic formula.

The roots are found to be  $-1 - j$  and  $-1 + j$ .

If we use these complex roots in the partial fraction expansion, the algebra can get quite tedious

$$x(s) = \frac{2}{s(s^2 + 2s + 2)} = \frac{A}{s} + \frac{Bs + C}{s^2 + 2s + 2}$$

Note that the second term of the expansion has the unfactored quadratic in the denominator.

$$A = \frac{2}{0 + 2(0) + 2} = 1$$

$$x(s) = \frac{2}{s(s^2 + 2s + 2)} = \frac{1}{s} + \frac{Bs + C}{s^2 + 2s + 2}$$

$$2 = s^2 + 2s + 2 + Bs^2 + Cs$$

$$(B + 1)s^2 + (2 + C)s + 2 = 2$$

$$s^2: B + 1 = 0 \quad B = -1$$

$$s: 2 + C = 0 \quad C = -2$$

$$x(s) = \frac{1}{s} - \frac{s + 2}{s^2 + 2s + 2}$$

$$x(s) = \frac{1}{s} - \frac{s + 2}{(s + 1)^2 + 1}$$

$$L\{e^{-at} \sin(kt)\} = \frac{k}{(s + a)^2 + k^2}$$

$$L\{e^{-at} \cos(kt)\} = \frac{s + a}{(s + a)^2 + k^2}$$

$$x(s) = \frac{1}{s} - \frac{(s + 1) + 1}{(s + 1)^2 + 1^2} = \frac{1}{s} - \frac{s + 1}{(s + 1)^2 + 1^2} - \frac{1}{(s + 1)^2 + 1^2}$$

$$x(t) = 1 - e^{-t}(\cos t + \sin t)$$

In the next example, an exceptional case is considered; the denominator of  $x(s)$  has *repeated roots*.

## Inversion of a transform with repeated roots

$$\frac{d^3x}{dt^3} + \frac{3d^2x}{dt^2} + \frac{3dx}{dt} + x = 1$$

$$x(0) = x'(0) = x''(0) = 0$$

$$x(s) = \frac{1}{s(s^3 + 3s^2 + 3s + 1)}$$

$$x(s) = \frac{1}{s(s+1)^3} = \frac{A}{s} + \frac{B}{(s+1)^3} + \frac{C}{(s+1)^2} + \frac{D}{s+1}$$

As in the previous cases, to determine  $A$ , multiply both sides by  $s$  and then set  $s$  to zero. This yields

$$A = 1$$

Multiplication of both sides of Eq. by  $(s+1)^3$  results in

$$\frac{1}{s} = \frac{A(s+1)^3}{s} + B + C(s+1) + D(s+1)^2$$



Setting  $s = -1$  in Eq. gives

$$B = -1$$

Having found  $A$  and  $B$ , we introduce these values into Eq. and place the right side of the equation over a common denominator;

$$\frac{1}{s(s+1)^3} = \frac{(s+1)^3 - s + Cs(s+1) + Ds(s+1)^2}{s(s+1)^3}$$

$$\frac{1}{s(s+1)^3} = \frac{(1+D)s^3 + (3+C+2D)s^2 + (2+C+D)s + 1}{s(s+1)^3}$$

$$1 = (1+D)s^3 + (3+C+2D)s^2 + (2+C+D)s + 1$$

$$1 + D = 0$$

$$3 + C + 2D = 0$$

$$2 + C + D = 0$$

Solving these equations  
gives

$C = -1$  and  $D = -1$ .

The final result is then

$$x(s) = \frac{1}{s} - \frac{1}{(s+1)^3} - \frac{1}{(s+1)^2} - \frac{1}{s+1}$$

$$x(t) = 1 - e^{-t} \left( \frac{t^2}{2} + t + 1 \right)$$

The result of Example may be generalized.

$$\frac{C_1}{(s+a)^n}, \frac{C_2}{(s+a)^{n-1}}, \dots, \frac{C_n}{s+a}$$

The other constants are determined by the method shown above Example. These terms lead to the following expression as the inverse transform:

$$\left[ \frac{C_1}{(n-1)!} t^{n-1} + \frac{C_2}{(n-2)!} t^{n-2} + \dots + C_{n-1} t + C_n \right] e^{-at}$$

### QUALITATIVE NATURE OF SOLUTIONS

If we are interested *only in the form* of the solution  $x(t)$ , *this information may be obtained directly from the roots of the denominator of  $x(s)$ .*

$$\frac{d^2x}{dt^2} + \frac{2'dx}{dt} + 2x = 2 \quad x(0) = x'(0) = 0$$

$$x(s) = \frac{2}{s(s^2 + 2s + 2)} = \frac{A}{s} + \frac{B}{s+1+j} + \frac{C}{s+1-j}$$

- Since the roots of the quadratic term are  $-1 \pm j$ ,
- $x(t)$  must contain terms of the form  $e^{-t} (C_1 \cos t + C_2 \sin t)$
- Alternatively, interested in the behavior of  $x(t)$  as  $t \rightarrow \infty$ .
- It is clear that the terms involving sin and cos vanish because of the factor  $e^{-t}$ .
- Therefore,  $x(t)$  ultimately approaches the constant, which by inspection must be unity.
- The qualitative nature of the solution  $x(t)$  can be related to the location of the roots of the denominator of  $x(s)$  in the complex plane.
- These roots are the roots of the characteristic equation.

# Nature of terms in the solution $x(t)$ based on roots in the denominator of $X(s)$

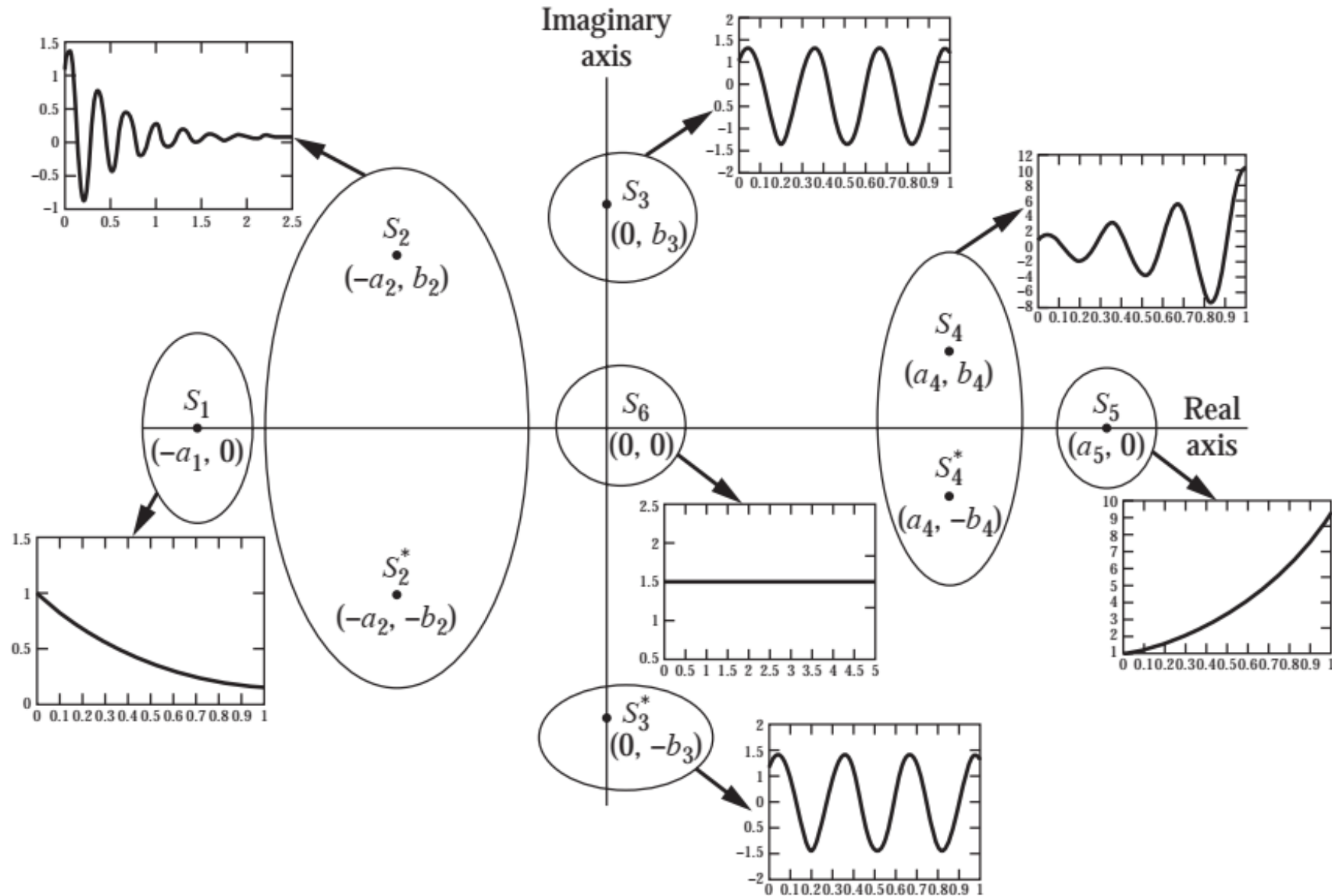
Roots in denominator of $X(s)$	Terms in $x(t)$ for $t > 0$
$s_1$	$C_1 e^{-a_1 t}$
$s_2, s_2^*$	$e^{-a_2 t} (C_1 \cos b_2 t + C_2 \sin b_2 t)$
$s_3, s_3^*$	$C_1 \cos b_3 t + C_2 \sin b_3 t$
$s_4, s_4^*$	$e^{a_4 t} (C_1 \cos b_4 t + C_2 \sin b_4 t)$
$s_5$	$C_1 e^{a_5 t}$
$s_6$	$C_1$

If any of these roots are repeated, the term given in Table is multiplied by a power series in  $t$

$$K_1 + K_2 t + K_3 t^2 + \dots + K_r t^{r-1}$$

where  $r$  is the number of repetitions of the root and the constants  $K_1, K_2, \dots, K_r$  can be evaluated by partial fraction expansion.

# Location of typical roots of characteristic equation



Any proper fraction may be resolved into a number of partial fractions subject to the following rules.

$$\frac{F(s)}{\underbrace{(as + b)^n}_{\text{root repeated } n \text{ times}}} = \underbrace{\frac{A_1}{as + b} + \frac{A_2}{(as + b)^2} + \dots + \frac{A_n}{(as + b)^n}}_{\text{there are } n \text{ partial fractions in expansion}}$$

$$\frac{F(s)}{\dots(as^2 + bs + c)\dots} = \frac{As + B}{\underbrace{as^2 + bs + c}_{\text{numerator is polynomial of one less degree than denominator}}} + \dots$$

$$\frac{F(s)}{\dots \underbrace{(as^2 + bs + c)^n}_{\text{yields } \rightarrow} \dots} = \underbrace{\frac{A_1s + B_1}{as^2 + bs + c} + \frac{A_2s + B_2}{(as^2 + bs + c)^2} + \dots + \frac{A_ns + B_n}{(as^2 + bs + c)^n} + \dots}_{n \text{ terms in expansion}}$$

## FINAL-VALUE THEOREM

- If  $f(s)$  is the Laplace transform of  $f(t)$ , then

$$\lim_{t \rightarrow \infty} [f(t)] = \lim_{s \rightarrow 0} [sf(s)]$$

provided that  $sf(s)$  does not become infinite for any value of  $s$  satisfying  $\text{Re}(s) \geq 0$ .

$$\int_0^{\infty} \frac{df}{dt} e^{-st} dt = sf(s) - f(0)$$

$$\lim_{s \rightarrow 0} \int_0^{\infty} \frac{df}{dt} e^{-st} dt = \lim_{s \rightarrow 0} [sf(s)] - f(0)$$

$$\int_0^{\infty} \frac{df}{dt} dt = \lim_{s \rightarrow 0} [sf(s)] - f(0)$$

$$\lim_{t \rightarrow \infty} [f(t)] - f(0) = \lim_{s \rightarrow 0} [sf(s)] - f(0)$$

- Find the final value of the function  $x(t)$  for which the Laplace transform is

$$x(s) = \frac{1}{s(s^3 + 3s^2 + 3s + 1)}$$

- Direct application of the final-value theorem yields

$$\lim_{t \rightarrow \infty} [x(t)] = \lim_{s \rightarrow 0} \frac{1}{s^3 + 3s^2 + 3s + 1} = 1$$

$$x(t) = 1 - e^{-t} \left( \frac{t^2}{2} + t + 1 \right)$$

Find the final value of the function  $x(t)$  for which the Laplace transform is

$$x(s) = \frac{s^4 - 6s^2 + 9s - 8}{s(s-2)(s^3 + 2s^2 - s - 2)}$$



$$sx(s) = \frac{s^4 - 6s^2 + 9s - 8}{(s + 1)(s + 2)(s - 1)(s - 2)}$$

Since this becomes infinite for  $s = 1$  and  $s = 2$ , the conditions of the theorem are

not satisfied.

Note that we

$$x(t) = -2 + \frac{1}{12}e^{2t} + \frac{11}{3}e^{-t} - \frac{17}{12}e^{-2t} + \frac{2}{3}e^t \text{ and that}$$

## INITIAL-VALUE THEOREM

$$\lim_{x \rightarrow 0} [f(t)] = \lim_{s \rightarrow \infty} [sf(s)]$$

Find the initial value  $x(0)$  of the function that has the transform

$$x(s) = \frac{s^4 - 6s^2 + 9s - 8}{s(s - 2)(s^3 + 2s^2 - s - 2)}$$

$$sx(s) = \frac{s^4 - 6s^2 + 9s - 8}{s^4 - 5s^2 + 4}$$

$$sx(s) = \frac{1 - 6/s^2 + 9/s^3 - 8/s^4}{1 - 5/s^2 + 4/s^4}$$

$$X(0) = 1$$

## TRANSLATION OF TRANSFORM

If  $L\{f(t)\} = f(s)$ , then

$$L\{e^{-at} f(t)\} = f(s + a)$$

*Proof*

$$L\{e^{-at} f(t)\} = \int_0^{\infty} f(t)e^{-at} e^{-st} dt = \int_0^{\infty} f(t)e^{-(s+a)t} dt = f(s + a)$$

Find  $L\{e^{-at} \cos kt\}$ . Since

$$L\{\cos kt\} = \frac{s}{s^2 + k^2}$$

- A primary use for this theorem is in the inversion of transforms. For example, by using this theorem the transform

$$x(s) = \frac{1}{(s + a)^2}$$

as  $L\{t\} = \frac{1}{s^2}$        $x(t) = te^{-at}$

## TRANSLATION OF FUNCTION

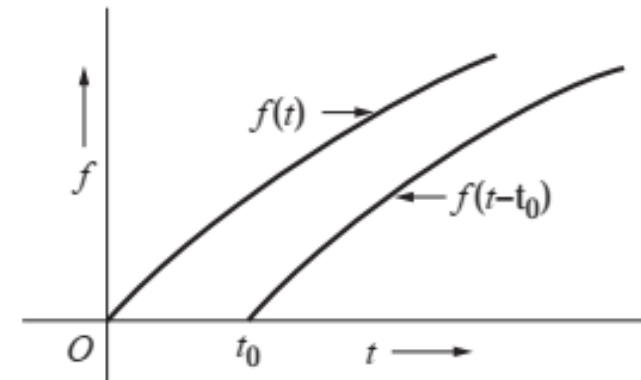
If  $L\{f(t)\} = f(s)$ , then

$$L\{f(t - t_0)\} = e^{-st_0} f(s)$$

$$f(t) = 0 \quad \text{for } t < 0$$

*Proof.*

$$\begin{aligned} L\{f(t - t_0)\} &= \int_0^{\infty} f(t - t_0) e^{-st} dt \\ &= e^{-st_0} \int_{-t_0}^{\infty} f(t - t_0) e^{-s(t-t_0)} d(t - t_0) \end{aligned}$$



## TRANSFORM OF AN INTEGRAL

- If  $L \{ f( t ) \} = f( s )$ , then

$$L \left\{ \int_0^t f(t) dt \right\} = \frac{f(s)}{s}$$

- This important theorem is closely related to the theorem on differentiation.
- Since the operations of differentiation and integration are inverses of each other when applied to the time functions,

$$\frac{d}{dt} \int_0^t f(t) dt = \int_0^t \frac{df}{dt} dt = f(t)$$

- It is to be expected that these operations when applied to the transforms will also be inverses.

$$s \frac{f(s)}{s} = \frac{1}{s} s f(s) = f(s)$$

**Solve the following equation for  $x(t)$ .**

$$\frac{dx}{dt} = \int_0^t x(t) dt - t$$

$$x(0) = 3$$

$$sx(s) - 3 = \frac{x(s)}{s} - \frac{1}{s^2}$$

$$x(s) = \frac{3s^2 - 1}{s(s^2 - 1)} = \frac{3s^2 - 1}{s(s + 1)(s - 1)}$$

$$x(s) = \frac{1}{s} + \frac{1}{s + 1} + \frac{1}{s - 1}$$

$$x(t) = 1 + e^{-t} + e^t$$

**Relationship between unit step and unit impulse:**

$$\int_0^{\infty} \delta(t) dt = u(t)$$

and  $\frac{du(t)}{dt} = \delta(t)$

Use the theorem for the transform of an integral to determine the transform of the unit-step function if we know that  $L\{d(t)\} = 1$

$$u(t) = \int_0^{\infty} \delta(t) dt, \text{ then}$$

$$L\{u(t)\} = L\left\{\int_0^{\infty} \delta(t) dt\right\} = \frac{1}{s}L\{\delta(t)\} = \frac{1}{s}$$

cross check: since we know that  $du(t)/dt = d(t)$ ,  
then

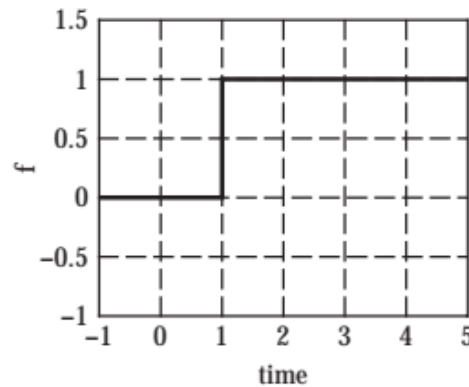
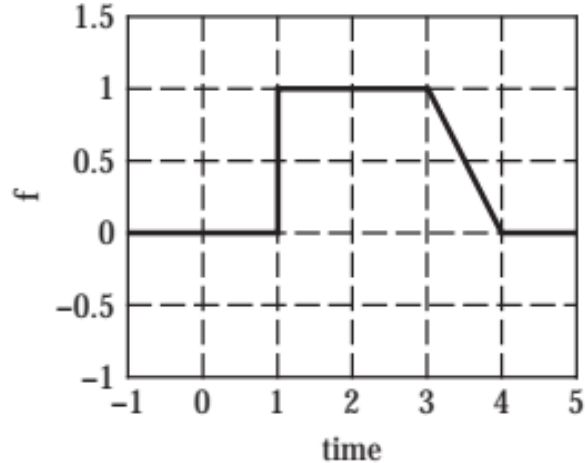
$$L\{\delta(t)\} = L\left\{\frac{du(t)}{dt}\right\} = sL\{u(t)\} = s \cdot \frac{1}{s} = 1$$

# CUSTOM INPUTS

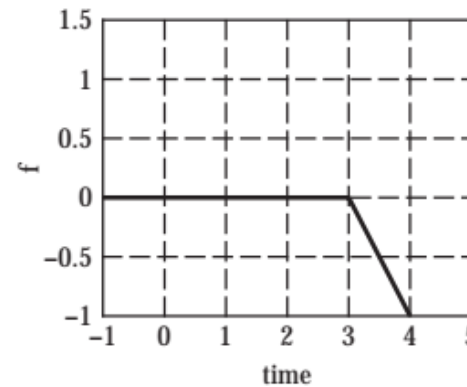
- We can produce “custom” input signals by appropriately constructing them using standard input signals.
- These custom inputs are frequently useful when we analyze a process disturbance.

We can consider this input signal to be constructed from several individual “pieces,”

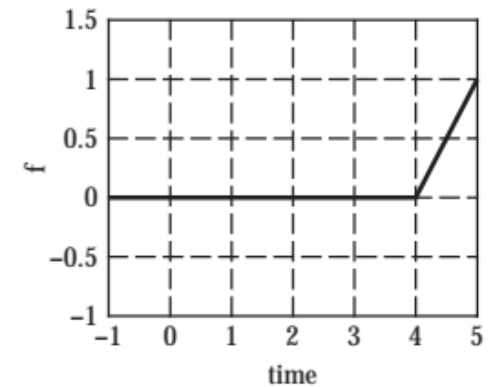
$$f(t) = u(t - 1) - (t - 3)u(t - 3) + (t - 4)u(t - 4)$$



Start with this piece . . .



Add this piece . . .



Then add this piece.