

Kinematics and Mechanism (MEE-S203)

Semester: 2022-23 (Even Semester)

Year: 2nd Year (2K21)

End Semester Examination

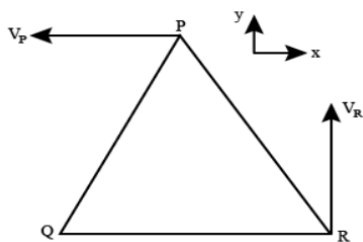
Time: 3 h

Maximum marks: 50

All questions are compulsory

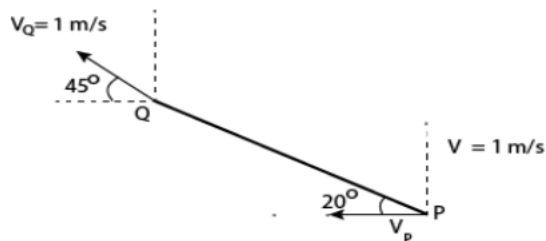
Section A

1. A rigid triangular body PQR, with sides of equal length of 1 unit moves on a flat plane. At the instant shown, edge QR is parallel to the x-axis, and the body moves such that velocities of points P and R are V_P and V_R , in the x and y directions, respectively. The magnitude of the angular velocity of the body is



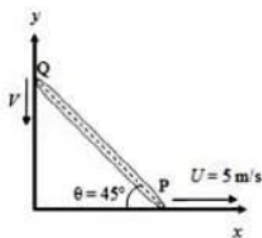
[2]

2. A rigid link PQ is 2m long and oriented at 200° to the horizontal as shown in the figure. The magnitude and direction of velocity V_Q , and the direction of velocity V_P are given. The magnitude of V_P (in m/s) at this instant is



[2]

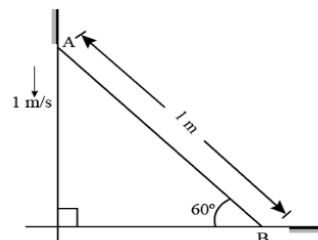
3. A rigid rod of length 1m is resting at an angle $\theta = 45^\circ$ as shown in figure. The end P is dragged with a velocity of $v_p = 5$ m/s to the right. At the instant shown, the magnitude of the velocity V_Q (in m/s) of point Q as it moves along the wall without losing contact is



[2]

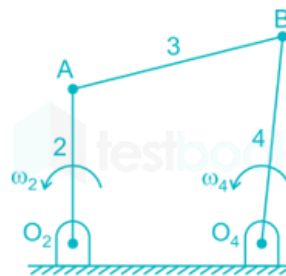
4. A rod of length 1 m is sliding in a corner as shown in figure. At an instant when the rod makes an angle of 60° with the horizontal

plane, the velocity of point A on the rod is 1 m/s. The angular velocity of the rod at this instant is 1 m/s.



[2]

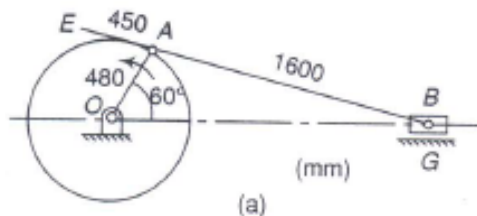
5. A four bar mechanism is shown in the figure. The link numbers are mentioned near the links. Input link 2 is rotating anticlockwise with a constant angular speed ω_2 . Length of different links are : $O_2O_4 = O_2A = L$, $AB = O_4B = \sqrt{2}L$. The magnitude of the angular speed of the output link 4 is ω_4 at the instant when link 2 makes an angle of 90° with O_2O_4 as shown. The ratio $\frac{\omega_4}{\omega_2}$ is _____.



[2]

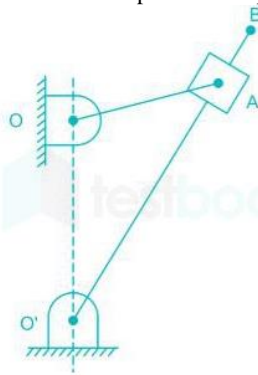
Section B

1. For the configuration of a slider –crank mechanism, calculate the
(a) Velocity of slider B
(b) angular velocity of link AB
OA rotates at 20 rad/s counter-clockwise.



[4]

2. A simple quick return mechanism is shown in the figure. The forward to return ratio of the quick return mechanism is 2 : 1. If the radius of the crank O_1P is 125 mm, then the distance 'd' (in mm) between the crank centre to lever pivot centre point should be



[4]

3. Derive the expression of coriolis acceleration.

[4]

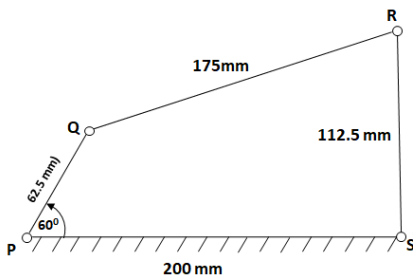
4. Define the following terms

- (a) module
- (b) circular pitch
- (c) path of contact
- (d) contact ratio

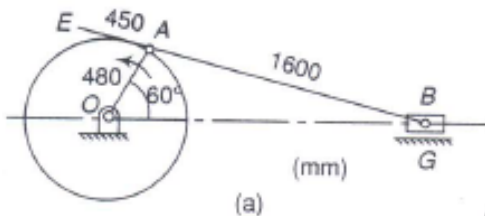
[4]

5. Locate instantaneous centre of rotation of given mechanism

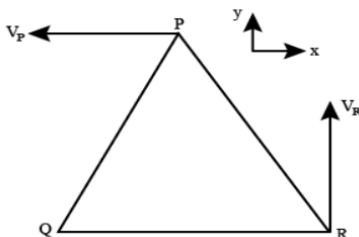
(a)



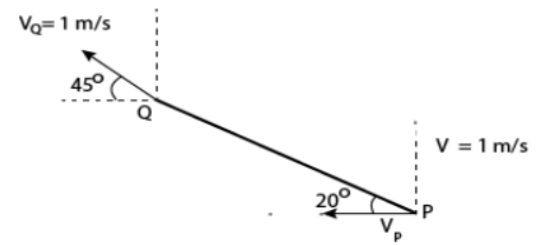
(b)



(c)



(d)

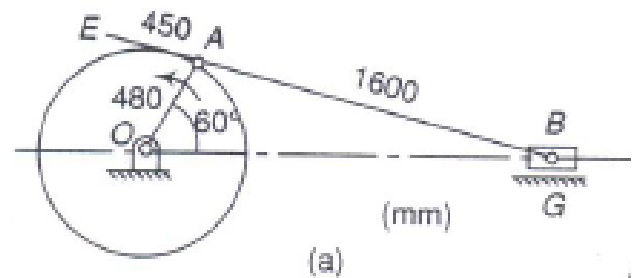


[4]

Section C

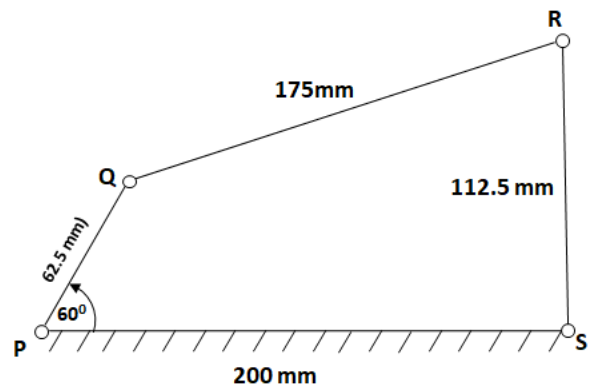
1. For the configuration of a slider –crank mechanism, calculate the

- (a) Acceleration of the slider at B
 - (b) Angular acceleration of the link AB
- OA rotates at 20 rad/s counter-clockwise.



[10]

2. PQRS is a four bar chain with link PS fixed. The lengths of the links are $PQ = 62.5$ mm ; $QR = 175$ mm ; $RS = 112.5$ mm and $PS = 200$ mm. The crank PQ rotates at 10 rad/s clockwise. when angle $QPS = 60^\circ$ and Q and R lie on the same side of PS. Find the angular velocity and angular acceleration of links QR and RS.



[10]