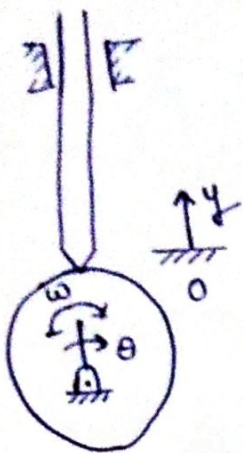


Displacement Diagram -



(i) Displacement of follower is moving with uniform velocity.

$$y = f(\theta)$$

$$= f(\omega t)$$

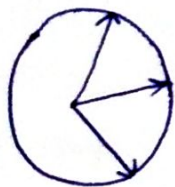
$$y = at + c$$

$$y = a.$$

$$\omega = \frac{d\theta}{dt}$$

$$\omega = \frac{\theta}{t}$$

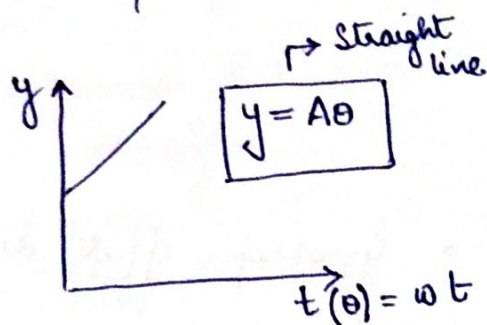
$$\theta = \omega t$$



$$y = \frac{dy}{d\theta} = c$$

$$y = ct + c_0$$

$$y = \left(\frac{c}{\omega}\right)t + c_0$$



(ii) Uniform acceleration -

$$a = c$$

$$\frac{d^2y}{dt^2} = c$$

$$\frac{dy}{dt} = ct + B$$

$$y = \frac{ct^2}{2} + Bt + D$$

$$= \frac{c}{2} \left(\frac{\theta}{\omega}\right)^2 + Bt + D$$

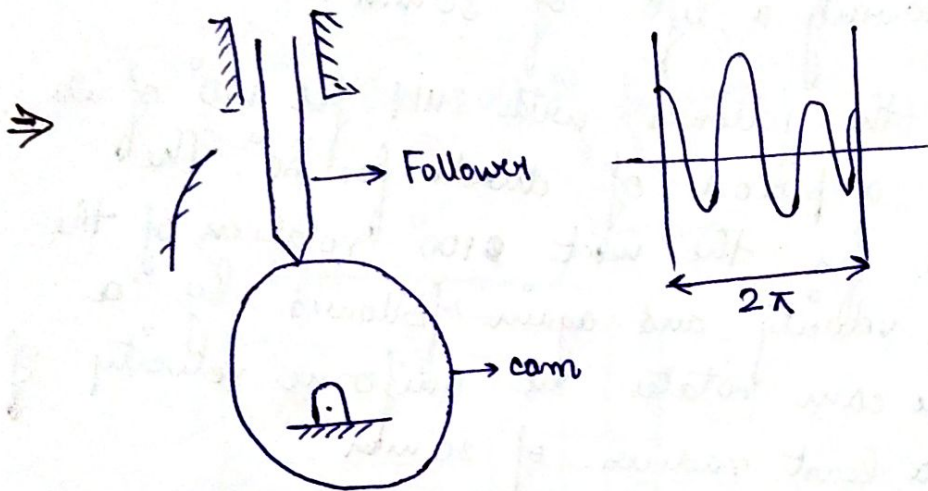
$$y = a\theta^2 + b\theta + c$$

↳ Parabolic

(iii) The motion of the follower is in SHM -

$$y = A \sin(\omega t + \phi) + C$$

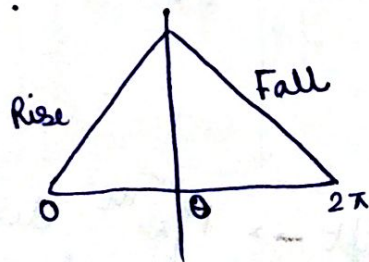
(iv) The motion of the follower is cycloidal -



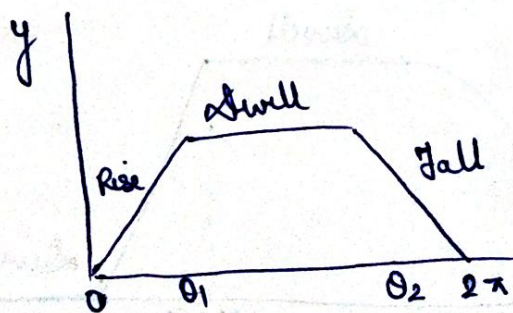
Classification of follower motion -

(i) Rise-fall -

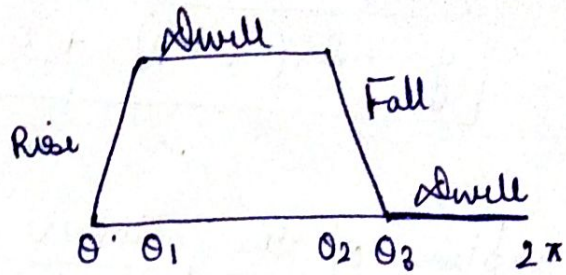
follower rises till particular angle & then fall after that angle.



(ii) Rise - Dwell - Fall -

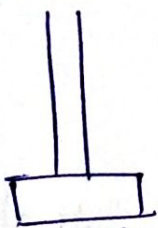


(iii) Rise - dwell - fall - dwell -



Q) Draw the profile of a cam of operating a knife edge follower having a lift of 30 mm.

The cam raises the follower with SHM for 150° of its rotation followed by a period of dwell for 60° . The follower descended for the next 100° rotation of the cam with uniform velocity and again followed by a dwell period. The cam rotates at uniform velocity of 120 rpm and has a least radius of 20 mm.



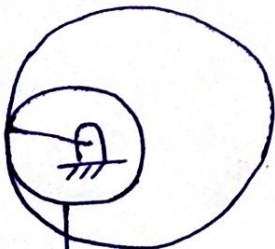
↳ flat plate



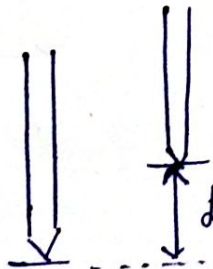
↳ roller follower



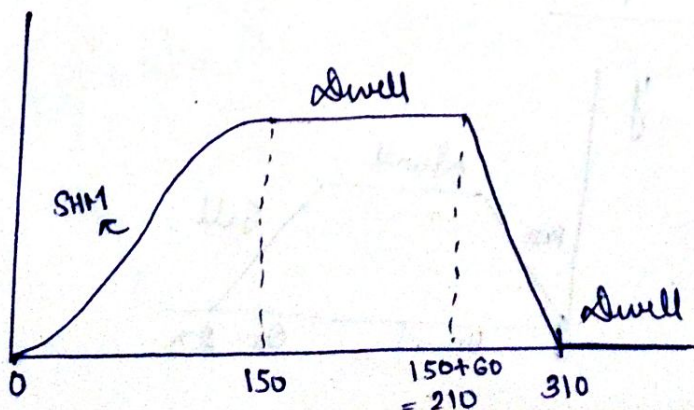
↳ knife edge.

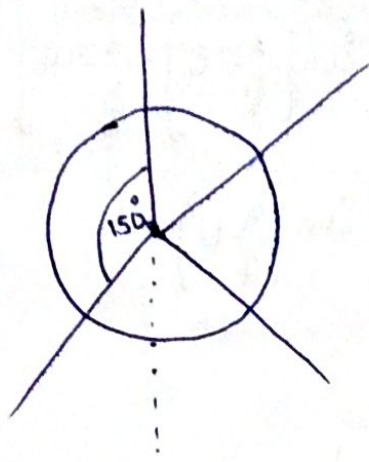


Base circle of cam



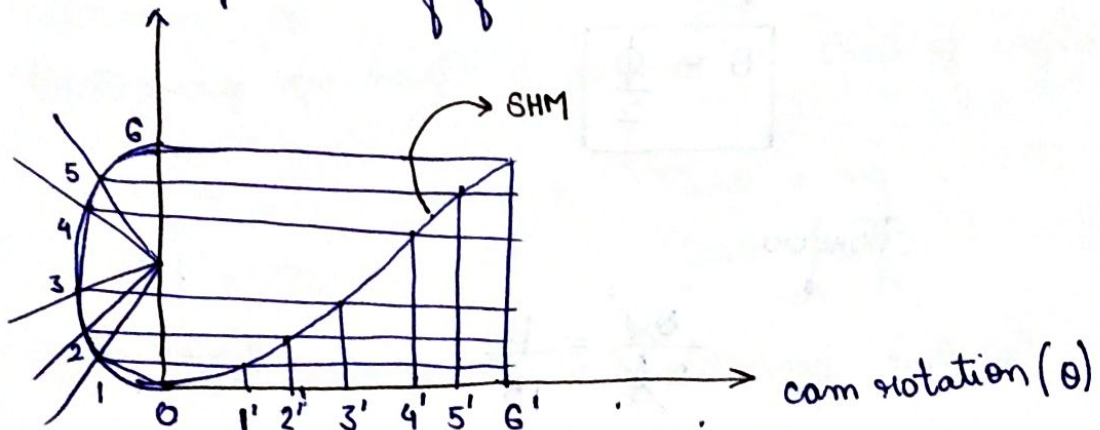
Max^m distance moved by the follower





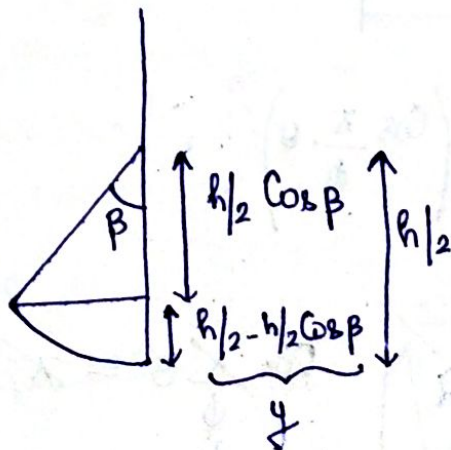
$$G_{cm} = 150^\circ$$

Displacement of follower



$$0 \leq \theta \leq \phi$$

$$0 \leq \beta \leq \pi$$



$$y = \frac{R}{2} - \frac{h}{2} \cos \beta$$

$$\frac{\theta}{\phi} = \frac{\beta}{\pi}$$

$$\beta = \frac{\theta \cdot \pi}{\phi}$$

$$\Rightarrow y = \frac{R}{2} - \frac{R}{2} \cos \left(\frac{\theta \cdot \pi}{\phi} \right)$$

$$y = f(\theta)$$

$$\frac{dy}{dt} = \frac{df(\theta)}{d\theta} = \frac{df(\theta)}{d\theta} \times \frac{d\theta}{dt}$$

$$\frac{dy}{dt} = f'(\theta) \cdot \omega$$

$$v = \frac{dy}{dt} = \frac{h}{2} \left[0 + \sin\left[\frac{\pi}{\phi} \cdot \theta\right] \cdot \frac{\pi}{\phi} \cdot \omega \right]$$

$$v = \frac{h}{2} \cdot \frac{\pi}{\phi} \omega \cdot \sin\left(\frac{\pi}{\phi} \theta\right)$$

$v_{\max} \rightarrow$

$$\frac{\sin \pi \cdot \theta}{\phi} = 1$$

$$\frac{\pi \theta}{\phi} = \frac{\pi}{2}$$

$$\boxed{\theta = \frac{\phi}{2}}$$

Therefore,

$$\frac{\theta \phi}{2 \phi} = \frac{\beta}{\pi}$$

$$\boxed{\beta = \frac{\pi}{2}}$$

$$a = \ddot{y} = \frac{h}{2} \frac{\pi^2}{\phi^2} \cdot \omega^2 \left(\cos \frac{\pi}{\phi} \cdot \theta \right)$$

$a_{\max} \rightarrow$

$$\cos \frac{\pi}{\phi} \cdot \theta = 0$$

$$\boxed{\theta = 0}$$

$$\cos \frac{\pi}{\phi} \theta = \pi$$

$$\boxed{\phi = \theta}$$